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The DOI for this manuscript is

DOI:10.2151/jmsj.2021-025

J-STAGE Advance published date: January 13th, 2021

The final manuscript after publication will replace the preliminary version at the above DOI once it is available.

1 A case study of a quasi-stationary, very long Polar Stratospheric Cloud layer edge

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6

7 Keywords: troposphere, stratosphere, polar stratospheric clouds, mountain gravity waves

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9

10 **Abstract**

11 A case study of occurrence of polar stratospheric clouds (PSCs) on February 13th, 2017 in
12 northern Sweden is discussed in the present paper. For the first time a quasi-stationary edge of a
13 bright and extended PSCs layer (~600 km long) on the Eastern side of the Scandinavian Mountain
14 Range was photographed as well as registered with lidar observations. Both lidar measurements and
15 model simulations demonstrated that atmospheric conditions were fairly unchanged for several
16 hours during the presence of the PSC. Strong winds across the Scandinavian Mountain Range were
17 responsible for triggering the formation of mountain lee waves in the Kiruna area, which in turn
18 induced the formation of the quasi-stationary long and straight edge of the PSCs.

19

20 **1. Introduction**

21 Polar Stratospheric Clouds (PSCs) are a common phenomenon during Arctic and Antarctic
22 wintertime. Their formation requires the stratospheric temperature to fall below ~ 195K (see e.g.
23 Browell et al., 1990; Tabazadeh et al., 1994; Larsen et al., 1997). The formation temperature is
24 usually only reached inside the polar vortex. Temperatures over the Arctic tend to be higher than
25 over Antarctica since the Arctic vortex is more unstable. Therefore PSCs occur more frequently
26 over Antarctica (Maturilli et al., 2005; Tilmes et al., 2006; Spang et al., 2016). This also means that

27 PSC formation in the Arctic is more strongly influenced by atmospheric disturbances such as waves
28 (Carslaw et al., 1998; Kohma and Sato, 2011; Alexander et al., 2013). Sources for waves can be
29 wind shear in the troposphere (e.g. the polar jet stream) or topographic features like ridges or
30 mountain chains. One well-known, and well-documented source in Northern Europe is the
31 Scandinavian Mountain Range (see e.g. Dörnbrack and Leutbecher, 2001; Blum et al., 2004;
32 Kirkwood et al., 2010; Kaifler et al., 2017). Waves originating at the mountain range are known to
33 produce temperature modulations due to vertical motion of air which allow the formation of PSCs
34 at certain locations downstream (Voigt et al., 2000; Dörnbrack et al., 2002).

35 In an ideal case the uniform flow across a straight mountain ridge should result in a wave-like
36 modulation of temperature downstream, with no variations parallel to the ridge. This would lead to
37 long crests of clouds (see e.g. Fig. 16 of Fritts and Alexander, 2003). In reality clouds in the lee of
38 the Scandinavian Mountain Range have more complex, patchy structures. Reasons are
39 inhomogeneities in the horizontal wind field (horizontal wind shears), either due to local
40 topographic effects or mesoscale variations. PSCs over Kiruna have been documented
41 photographically for many years (see https://doi.org/10.34474/data.jmsj.133845**.v*
42 and <http://data.irf.se/data/dalin2020psc>). Based on those observations it can be concluded that
43 clouds with patchy structures are common over Kiruna, while well-defined cloud boundaries are a
44 rare exception.

45 In the present paper we discuss an unusual case in which a PSC layer, that formed due to
46 mountain lee waves, had an extended edge and remained stationary over a rather long period of
47 time. In the following we will first explain the instruments and methods which are used in this
48 study. Thereafter, the observations are described, followed by an interpretation and a summary.

49

50 **2. Instruments and methods**

51 This study is based on a combination of optical observations and model data. Photographic
52 images were taken with a Canon G5 camera (resolution of 2592 x 1944 pixels) from the roof of the

53 main building of the Swedish Institute of Space Physics in Kiruna, Northern Sweden (IRF, located
54 at 67.84°N , 20.41°E). Lidar measurements were performed with a backscatter lidar located at IRF.
55 The lidar operates at a wavelength of 532 nm and has two detection channels to distinguish parallel
56 and perpendicular polarisation of the backscattered light. The altitude range for observations is 5 to
57 50 km. Height and time resolution are 30 m and 133 s, respectively (see Voelger and Nikulin (2005)
58 for more details).

59 For interpretation of atmospheric conditions during the period of interest, simulations with the
60 Weather Research and Forecasting (WRF) model (Skamarock et al., 2008) were performed. WRF
61 allows the calculation of the state of the atmosphere on a user-defined 3D grid for chosen time
62 steps. As input for WRF we used ERA5 reanalysis data from the European Centre for Medium-
63 Range Weather Forecasts (ECMWF). ERA5 data has a horizontal resolution of 31 km and 137
64 vertical levels (Hersbach et al., 2020).

65

66 **3. Observational data**

67 Images of a Polar Stratospheric Cloud were taken in Kiruna (67.84°N , 20.41°E) during the
68 afternoon of February 13th, 2017 (Fig. 1). The cloud edge was unusual in that (a) it remained at the
69 same location for several hours (at least during the period of visual and photographic observations
70 14-17 UT, corresponding to 15-18 LT) and (b) it was long and straight (modulated with filaments)
71 along a line from southwest to northeast as long as about 600 km at least. Based on geographical
72 features on the photographic images (e.g. mountains and the position of the sunset) it was possible
73 to determine the angle between geographical north and cloud edge to be $44^{\circ}\pm 5^{\circ}$ (Fig. 2). At the
74 same time winds were consistently blowing from directions between north and northwest, hence
75 approximately along the normal of the cloud edge. Wind speed at the ground was between 6 and 8
76 m/s as recorded by IRF's weather station. Such wind conditions are favourable for the formation of
77 mountain gravity waves on the lee side of the Scandinavian Mountain Range, i.e. on its eastern side.
78 This strengthens the assumption that the cloud frontal shape is a result of mountain gravity waves.

79 During the following night IRFø's backscatter lidar was performing measurements 1 km south of
 80 the location where the photos were taken. The lidar operated from 17 UT until next morning 04:45
 81 UT. Backscatter signals with both parallel and perpendicular polarisation were recorded. During the
 82 whole observation period a cloud layer was present in the stratosphere between 24 and 27 km
 83 altitude (Fig. 3). In lidar measurements PSCs can be characterized by (a) the depolarisation ratio
 84 $= I_{perp} / I_{par}$ with I being the measured backscatter intensity of the parallel and perpendicular
 85 channel, respectively, and (b) the backscatter ratio R , defined as $R = (\beta_{psc} + \beta_{mol}) / \beta_{mol}$ where β is
 86 the backscatter coefficient for PSCs and molecules, respectively. The combination of R and
 87 allows for the determination of the chemical composition of the cloud (see Browell et al., 1990 for
 88 details). In the case discussed here the combination of both large backscatter ratio and large
 89 depolarisation ratio indicated that the cloud consisted of ice particles. Over Northern Scandinavia
 90 such clouds most times only are formed in connection with mountain gravity waves (Blum et al.,
 91 2005).

92

93 4. Data Analysis

94 In order to put our local observations in a regional context we examined atmospheric conditions
 95 with help of WRF simulations. The model grid covered the northern part of Fennoscandia with 5.4
 96 km distance between horizontal grid points and 160 height levels up to 10 hPa (see Fig. 2 for area
 97 covered by grid). Simulations were performed for a period of 96 hours, starting 48 hours before the
 98 photos were taken. Time resolution of output was set to 10 min.

99 Figure 4 shows simulated wind and temperature fields at 25 km altitude for times 12 and 18 UT
 100 on date 13/02/17 and at 00 UT on date 14/02/17, as derived with WRF. During all three times wind
 101 directions north of 65°N were roughly perpendicular to the Scandinavian Mountain Range. Both
 102 wind speed and direction changed only marginally during this period. The wind field induced a
 103 wavelike horizontal quasi-stationary motion which resulted in a perturbation of the temperature
 104 field above and in the lee of the mountains. The position and orientation of the main temperature

105 minimum just behind the mountains corresponds well to the position of the PSC edge at 12 UT and
106 18 UT on February 13th, 2017. The orientation of the temperature minimum at 00 UT on February
107 14th corresponds less to the orientation of the PSC edge. Visual observation of the development of
108 the cloud edge was not possible at that time of the day due to darkness. However, our lidar
109 observations proved the continuing presence of a PSC layer. Additionally, the spaceborne lidar
110 CALIOP detected a PSC at approximately 69°N, 29°E while passing the Gulf of Bothnia east of
111 Kiruna during that night, shortly after 01 UT.

112 A commonly used indicator for the vertical stratification of the atmosphere is the buoyancy
113 frequency, N , also called the Brunt-Väisälä frequency (see e.g. Holton, 1992). Figure 5 illustrates a
114 cross section of N through the location of the ground-based observations and along the wind
115 direction at 18 UT. One can see that the first positive maximum is observed right above the
116 mountains at about 2 km, then other maxima occur at 14, 27-28, 37-39 km altitudes, hence a
117 vertical wavelength of the main mountain wave is about 10-12 km above the Kiruna area. The
118 upward direction of energy propagation can be seen from the vertical phase propagation directed
119 downward relative to the mean flow (which is from the left to right in Figure 5) and westward
120 relative to the mountains (Holton, 1992). Two buoyancy minima at 5 and 10 km as well as two
121 maxima at 14 and 28 km are directed westward relative to the mountain ridge and with height.
122 These phase tilts provide the evidence of the upward wave energy propagation as expected since the
123 energy source for these waves was located at the ground (mountains).

124 Figure 6 shows the temporal development of the buoyancy frequency near the mountain crest at
125 69°N, 19°E (left panel) and in the lee of the mountains at 67.84°N, 20.41°E (right panel). Here,
126 WRF was used to achieve better time resolution than with ERA5. At both locations vertical profiles
127 of N remained fairly unchanged for about 24 hours showing wave-like structures. In Fig. 7 a profile
128 for the buoyancy frequency near the mountain crest is displayed. While some temporal variation of
129 absolute numbers does occur, the height of the features varies only marginally. Estimating the
130 vertical length of the wave-like motion is straight forward. It was in the range of 10-12 km, both

131 above the mountain range and in the lee of the mountains where both photos were taken and lidar
 132 measurements were performed.

133 An apparently stationary wave in the lee of a mountain is a special case of a topographic wave
 134 (see e.g. Holton, 1992). For a wave to appear to be stationary its phase speed c has to be exactly the
 135 opposite of the speed of the mean flow \bar{u} . The dispersion relation for a stationary wave is then

$$136 \quad 0 = \bar{u} \pm \frac{N}{\sqrt{k^2 + m^2}} \quad (1)$$

137 Here, N is the buoyancy frequency, k and m are horizontal and vertical wavenumber, respectively.

138 Note that Figure 4 demonstrates the background wind which is quasi perpendicular to the PSC edge
 139 hence is almost parallel to the k vector. The equation can be simplified to

$$140 \quad m^2 = \frac{N^2}{\bar{u}^2} - k^2 \quad (2)$$

141 In our case the horizontal wavelength is longer than 200 km as one can see in Figure 4, hence

142 $k < N / \bar{u}$. For a wave with a vertical wavelength of 12 km to be created the horizontal wind speed
 143 needs to be ~ 40 m/s. This means that the stationary wave was created at an altitude range where
 144 horizontal wind speed is around that value, i.e. in the lower troposphere right above the mountains
 145 as demonstrated in Fig. 8. Figure 8 illustrates that the horizontal wind speed was varying around 40
 146 m/s in the range of 35-45 m/s between 2 and 15 km. Small amplitude modulations of the mean wind
 147 speed between 5 and 15 km are also seen due to interference with small-scale gravity waves. These
 148 small-scale modulations are also reproduced in the buoyancy frequency between 6 and 13 km seen
 149 in Fig. 7. Since the vertical wavelength m is a function of both the buoyancy frequency and mean
 150 wind speed (see Eq. 2), m might slightly change due to these small variations. However, the main
 151 period of the vertical wavelength of 10-12 km is unchanged and is clearly seen both in the
 152 buoyancy frequency (Fig. 7) and in the horizontal wind speed (Fig. 8) between 3 and 13 km. Note
 153 that the horizontal wind speed, along the horizontal wavenumber vector, does not approach to zero
 154 meaning that there were no any critical levels for mountain gravity waves propagating from the
 155 ground to the PSC altitude. The created mountain wave induced its own variations on the horizontal

156 wind speed, resulting in high variations in the horizontal wind speed at higher altitudes above 15
157 km, with maximum wind speed changes of ~40 m/s at the 30 km altitude. Thus, theoretical
158 considerations fit to WRF model wind data that confirm a principal possibility of the formation of a
159 stationary gravity wave above and in the lee of the mountains.

160

161 **5. Summary**

162 For the first time, a quasi-stationary very long (~600 km) and nearly straight Polar Stratospheric
163 Cloud edge was observed in Kiruna, Northern Sweden on February 13th, 2017. Both lidar
164 observations and simulations with WRF showed that atmospheric conditions were fairly unchanged
165 for several hours. At the same time strong winds across the Scandinavian Mountain Range were
166 present which triggered the formation of mountain lee waves in the Kiruna area. It was shown that
167 the stationary waves that could be observed were formed by horizontal winds with 40 m/s wind
168 speed. Such wind speeds were found in the lower troposphere at about 3 km altitude. Hence, the
169 waves that created the stationary cloud edge in the stratosphere propagated upwards from the lower
170 troposphere.

171

172 **Acknowledgment**

173 This study was conducted using resources provided by the Swedish National Infrastructure for
174 Computing (SNIC) at the High Performance Computing Center North (HPC2N), Umeå University,
175 Sweden. The observation data (PSC images and lidar measurements) related to this article can be
176 found at https://doi.org/10.34474/data.jmsj.133845**.v* and the project ftp server:
177 ftp://ftp.irf.se/outgoing/pdalin/PSC_2017/.

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247 **Figure captions:**

248 **Fig. 1.** Photos of PSC in WSW direction (left) and ENE direction (right), taken on February 13th,
249 2017 at 14:31 UT and 16:08 UT, respectively, in Kiruna (Sweden).

250

251 **Fig. 2.** Estimated front of the observed PSC based on sunset and on identification of topographic
252 features that are visible in the photos in Fig. 1. Thin black lines mark the edges of the grid used in
253 WRF simulations.

254

255 **Fig. 3.** Backscatter ratio (BSR) from lidar observations of the PSC layer as the function of time and
256 intensity on 13-14 February 2017. The backscatter signal in the parallel polarization channel is
257 shown.

258

259 **Fig. 4.** Horizontal maps of the wind velocity with wind vectors (left side) and temperature (right
260 side) fields at 25 km altitude for times 12 UT, 18 UT on February 13th and 00 UT on February 14th
261 as calculated by WRF. The black line (same as blue line in Fig. 2) marks the edge of the observed
262 PSC. White lines indicate the existence temperatures for NAT particles (solid, Hanson and
263 Mauersberger, 1988) and ice particles (dashed, Marti and Mauersberger, 1993).

264

265 **Fig. 5.** Buoyancy frequency variations calculated from ERA5 data as a function of the geographical
266 position through the observational point along the horizontal wind direction and altitude at 18 UT
267 on February 13th 2017. The horizontal axis gives the geographical coordinates along the cross
268 section parallel to horizontal wind direction. The vertical white line shows the position of the lidar
269 observational point. The height profile of the Scandinavian Mountain Range along the cross section
270 is shown in white at the bottom of the figure. The arrow indicates the direction of the horizontal
271 wind.

272

273 **Fig. 6.** Buoyancy frequency as a function of time as calculated with WRF. Left: near the mountain
274 crest, right: at location of lidar observations.

275

276 **Fig. 7.** Profile of buoyancy frequency derived as calculated with WRF for a location near the
277 mountain crest.

278

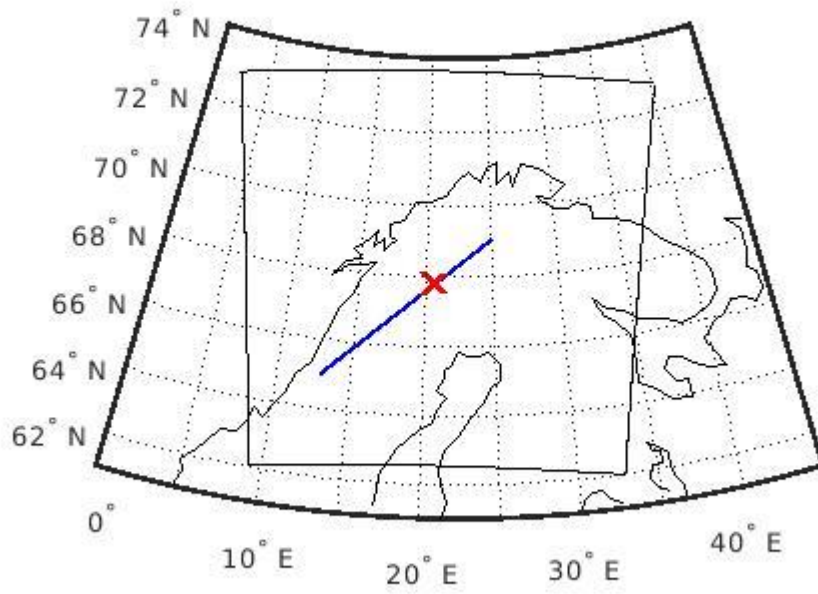
279 **Fig. 8.** Profile of horizontal wind speed perpendicular to the mountain crest (background horizontal
280 wind along the horizontal wavenumber vector) as calculated with WRF. The location of the profile
281 is near the mountain crest.

282 **Figures**

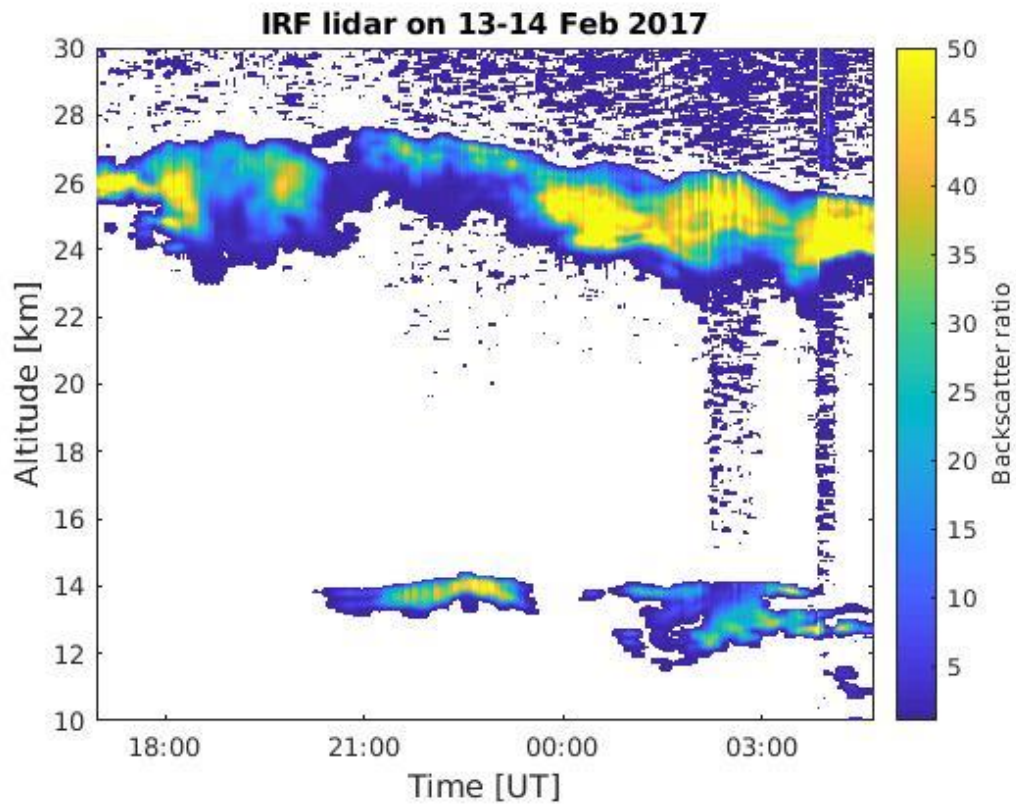


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284 **Figure 1.**

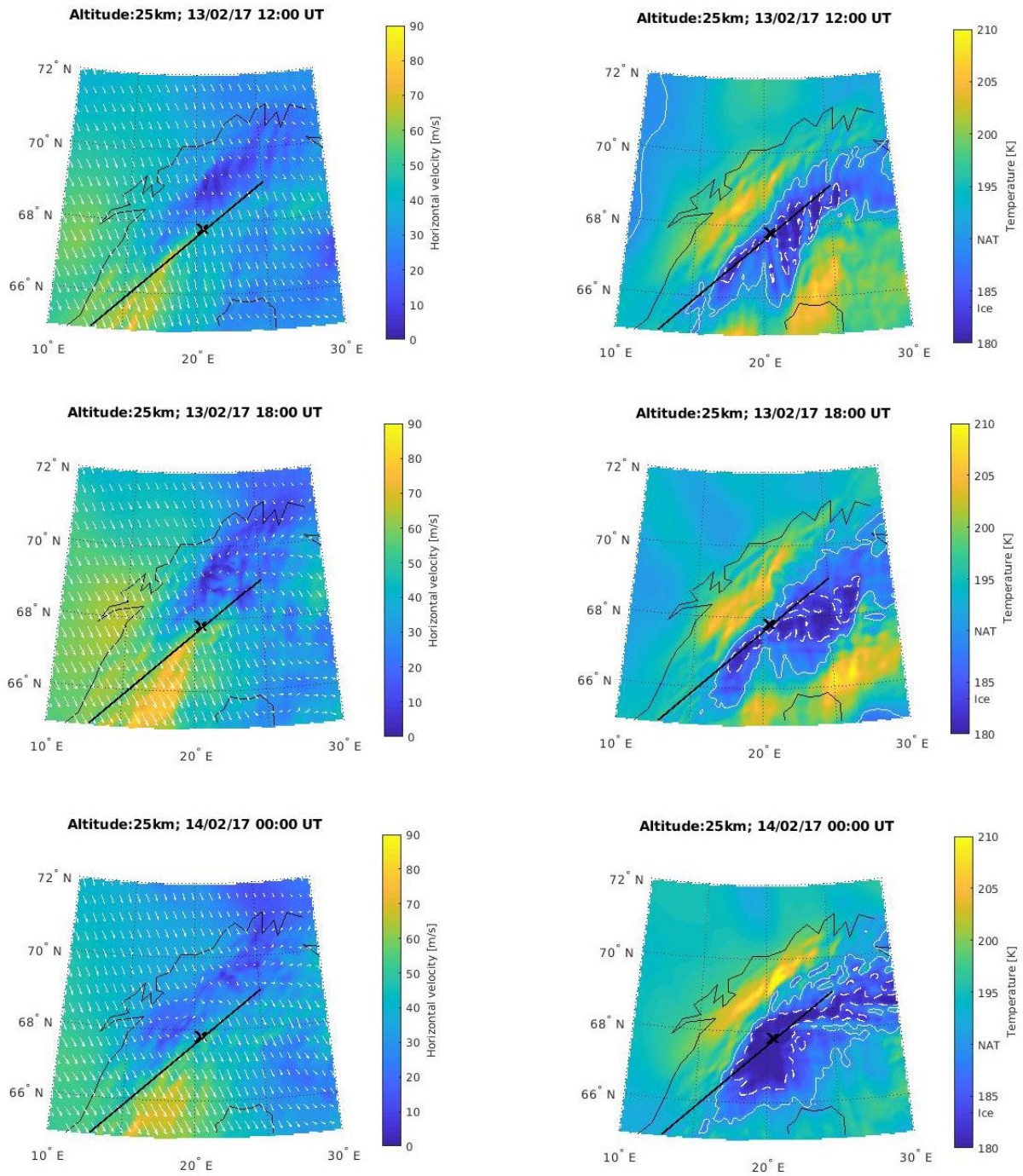


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286 **Figure 2.**



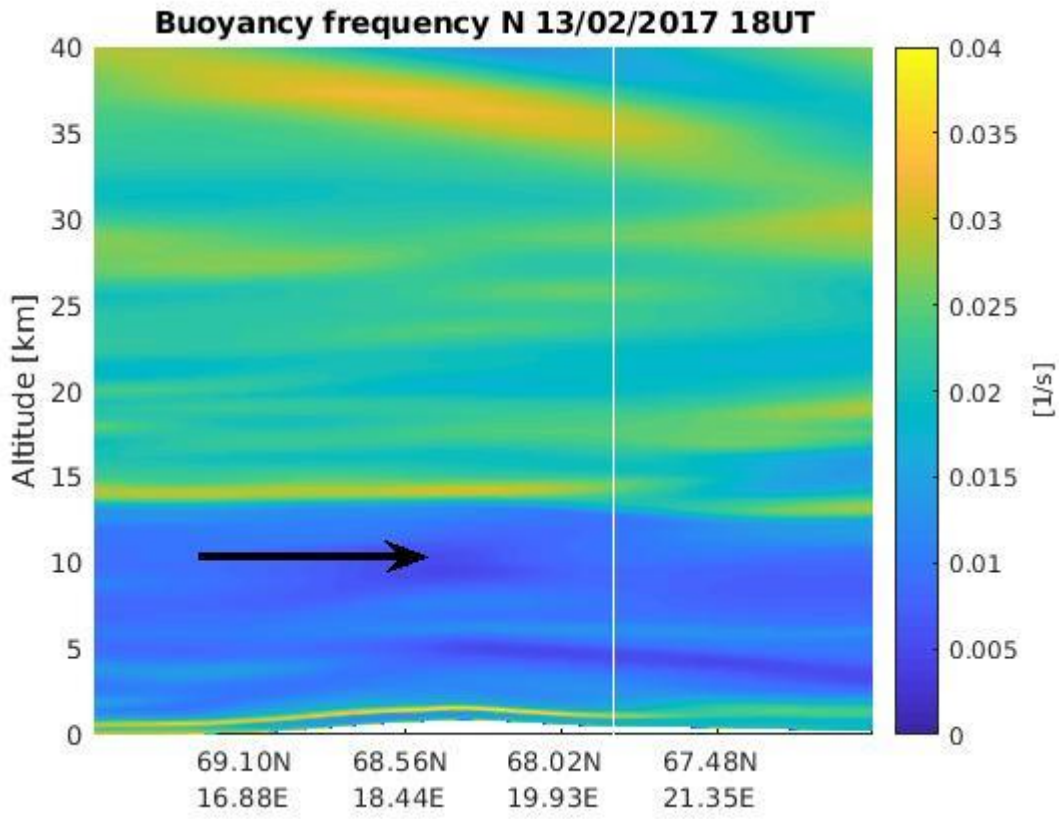
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288 **Figure 3.**

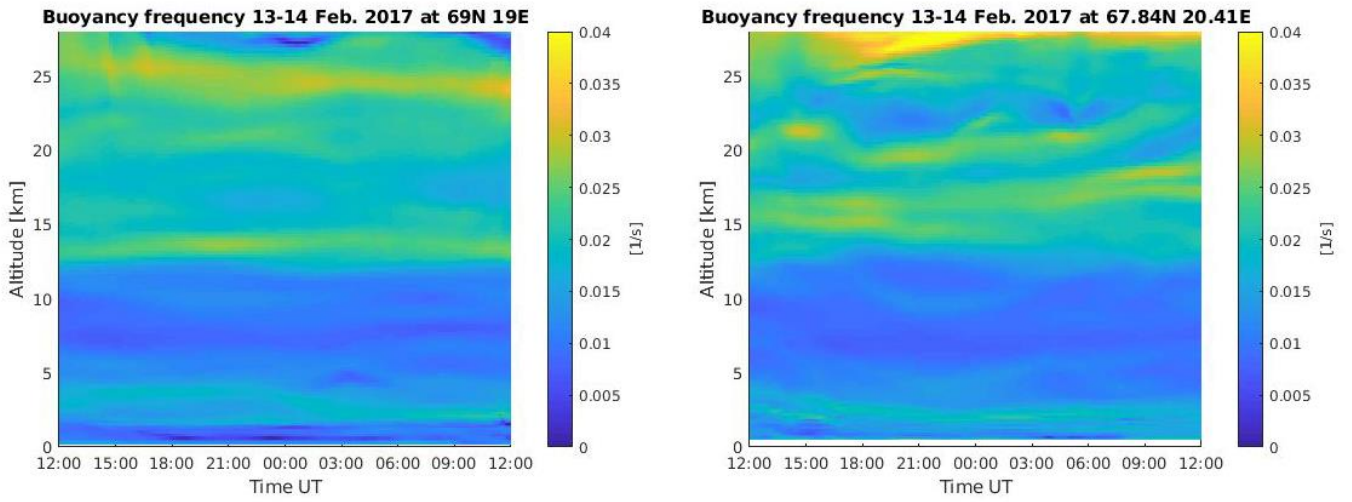


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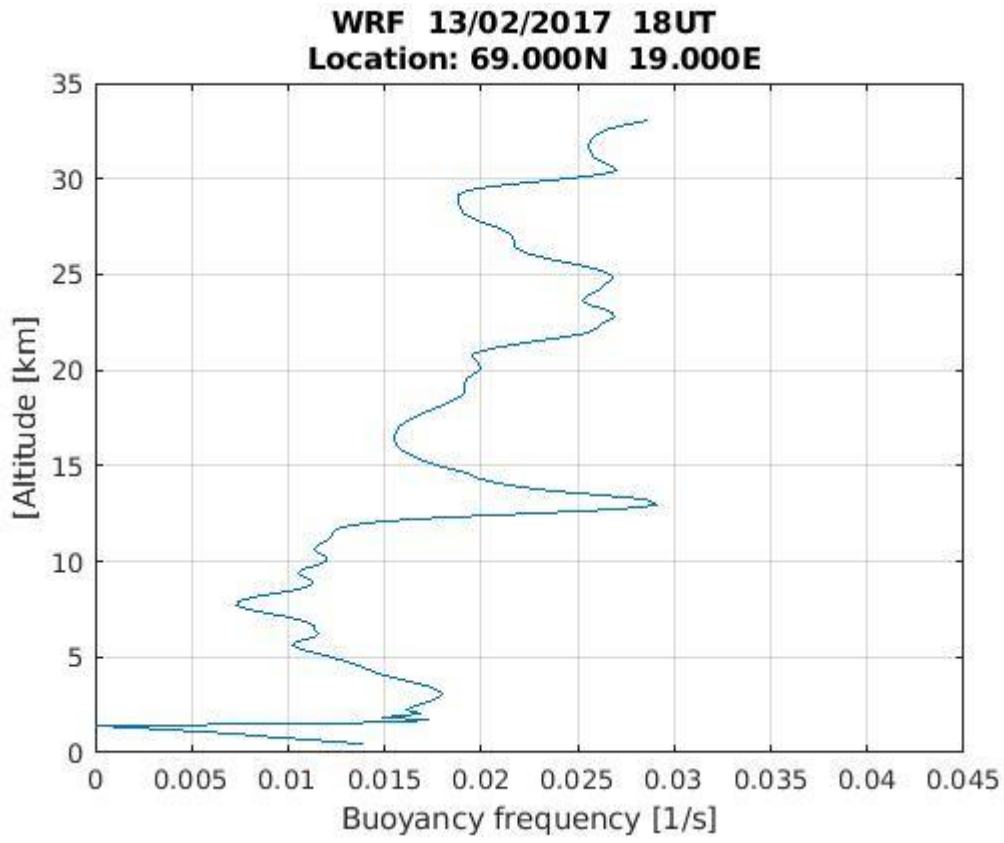
290 **Figure 4.**



291
292 **Figure 5.**
293



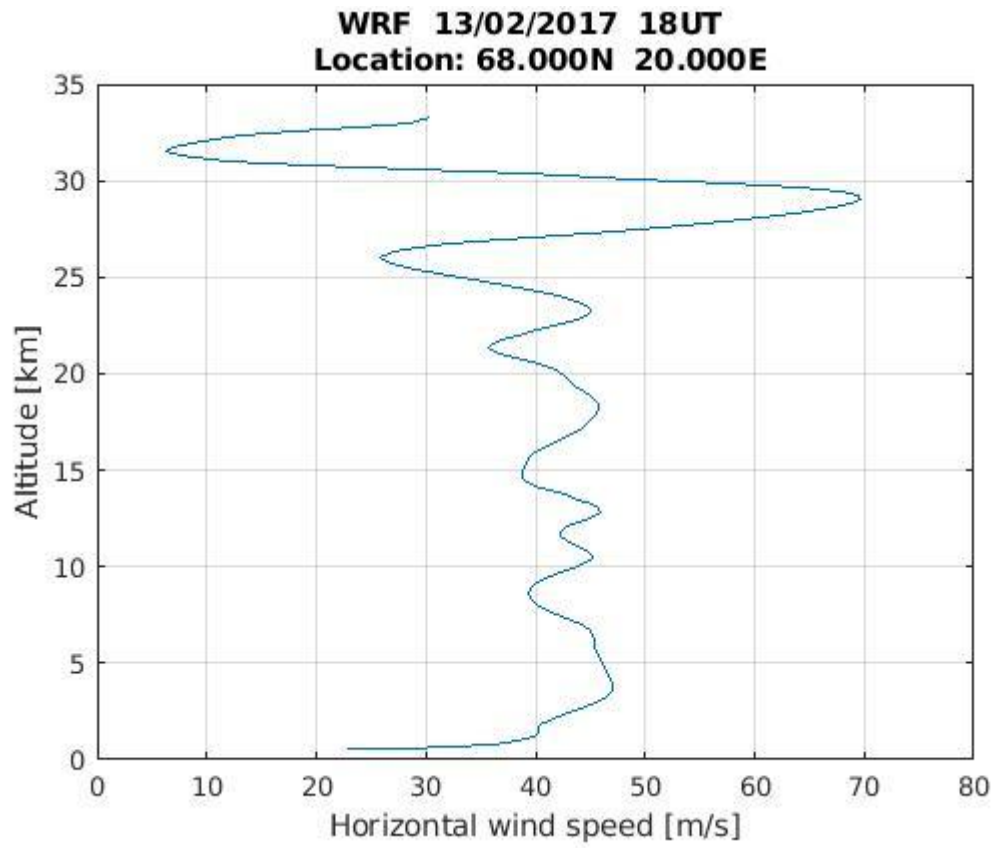
294
295 **Figure 6.**



296

297 **Figure 7.**

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299

300 **Figure 8.**

301